

# Result

The rover met three out of four standards for this challenge: temperature and humidity readings, detect light, and display information on a screen. There was not enough power to control all of the sensors, so I had to either add another power source or cut a sensor. I had to go with the latter because too much power could damage your components, a fact I learned all too well when the first Pi got fried. Overall, the project did better than I thought it would but it did not achieve what I wanted it to be.

I personally, looking back, don't like this conclusion, but oh well. That was for the deadline.

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